TPM CIRCLE NO :- 3	ACTIVITY	KK	QM	PM	JH	SHE	ОТ	DM	E&T
TPM CIRCLE NAME:	LOSS NO. / STEP								
DEPT :- Q.A	RESULT AREA	Р	Q	DEF :- A	A	С	D	S	М

CELL :-A289 Rotor | CELL NAME:- Traub

**KAIZEN THEME**:- To eliminate depth 1.2 variation in A157 body.

# COUNTERMEASURE:-

MACHINE / STAGE :- Traub

1)Scaling to be provided on Troub m/c to avoid setting rejection

**IDEA:** Scaling to be provided on Troub m/c to avoid setting rejection



Tool post modified with scaling & operator can easily take offset & avoid rejection

# BENCHMARK 42 No. TARGET 0 No. KAIZEN START 15.11.2014 TARGET DATE 14.12.2014 KAIZEN FINISH 14.12.2014

KAIZEN IDEA SHEET

# **TEAM MEMBERS:-**

Mr. Nana ugle ,Vishal chowghule, Mr. Vijay Walunj

**OPERATION:** Back facing operation

#### **BENEFITS:-**

- 1. To prevent Customer Complaint at customer end.
- 2. Reduce COPQ.

**AFTER** 

**WHAT TO DO-:-** Check point added in sustenance check sheet.

**KAIZEN SUSTENANCE** 

**HOW TO DO:-** By Checking.

**FREQUENCY**:- Alternate day.

### **COST INCURRED FOR MAKING KAIZEN**

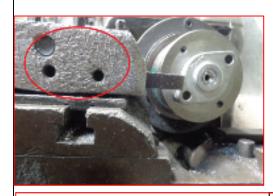
MATERIAL COST	LABOUR COST	TOTAL COST
IN RS	IN RS	IN RS

#### SCOPE & PLAN FOR HORIZONTAL DEPLOYMENT

SR. NO.	CELL	TARGET	RESPONSIBILITY	STATUS
1	A319, A216	15.10.15	Nana Ugale	Comple ted

# WIDELY/DEEPLY:-

# **PROBLEM / PRESENT STATUS:-.**



No Scaling to m/c to move tool holder on Z axis

**B**EFORE

### WHY - WHY ANALYSIS :-

**Why 1** – A157 Body  $1.2 \pm 0.1$  u/s & actual 1.05 mm.

**Why 2** – If operator found 1.2 depth oversize then operator hammering on tool post & then run m/c & check part if Ng again repeat that activity & rejection produce.

Why 3 – No scaling to troub m/c to move tool holder on Z axis.

**ROOT CAUSE-:-**— No scaling to troub m/c to move tool holder on Z axis.

REGISTRATION NO. & DATE:- 15.10.2014

**REGISTERED BY: - Ganesh Padwalkar** 

**MANAGER'S SIGN :- Sunil kinkar** 

#### **RESULT:-**

